

Speech
Modifications

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talk

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SPEECH MODIFICATIONS

LECTURE 3: HARMONIC PLUS NOISE MODELS AND MODIFICATIONS

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- MBE (Griffin et al.1988 [1])
 - Sinusoids plus band-pass random signals (Abrantes et al.1991 [2])
 - Harmonic and Stochastic Model (Laroche et al.1993 [3])
 - Iterative decomposition of the excitation signal (Yegnayarayana et al.1995 [4])
 - Harmonic plus Noise Model (Stylianou et al.1995 [5])
 - Harmonic plus Noise Model 2 (Stylianou, PhD, 1996 [6])

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Decomposing speech into (quasi)periodic and non-periodic part has many applications in:

- Speech modification
 - Speech coding
 - Pathologic voice detection (i.e., HNR ...)
 - Psychoacoustic research

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MOTIVATION FOR HNM

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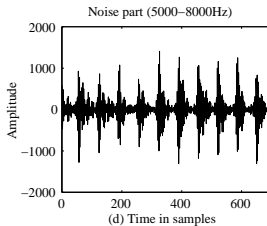
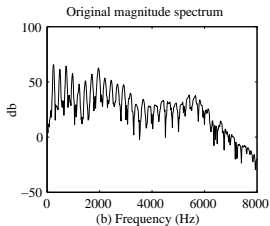
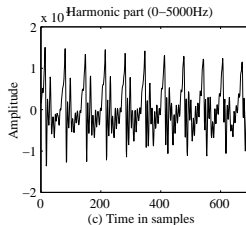
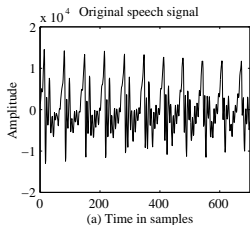
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BRIEF OVERVIEW OF HNM

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- HNM is a pitch-synchronous harmonic plus noise representation of the speech signal.
- Speech spectrum is divided into a low and a high band delimited by the so-called maximum voiced frequency.
- The low band of the spectrum (below the maximum voiced frequency) is represented solely by harmonically related sine waves.
- The upper band is modeled as a noise component modulated by a time-domain amplitude envelope.
- HNM allows high-quality copy synthesis and prosodic modifications.

HNM IN EQUATIONS

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- Harmonic part:

$$h(t) = \sum_{k=-L(t)}^{L(t)} A_k(t) e^{j k \omega_0(t) t}$$

- Noise part:

$$n(t) = e(t) [v(\tau, t) \star b(t)]$$

- Speech:

$$s(t) = h(t) + n(t)$$

PERIODIC PART

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- HNM₁: Sum of exponential functions without slope

$$h_1[n] = \sum_{k=-L(n_a^i)}^{L(n_a^i)} a_k(n_a^i) e^{j2\pi k f_0(n_a^i)(n-n_a^i)}$$

- HNM₂: Sum of exponential function with complex slope

$$h_2[n] = \Re \left\{ \sum_{k=1}^{L(n_a^i)} A_k(n) \exp^{j2\pi k f_0(n_a^i)(n-n_a^i)} \right\}$$

where

$$A_k(n) = a_k(n_a^i) + (n - n_a^i) b_k(n_a^i)$$

with $a_k(n_a^i)$, $b_k(n_a^i)$ to be complex numbers (amplitude and slope respectively). \Re denotes taking the real part.

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PERIODIC PART *continuing*

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- HNM₃: Sum of sinusoids with time-varying real amplitudes

$$h_3[n] = \sum_{k=0}^{L(n_a^i)} a_k(n) \cos(\varphi_k(n))$$

where

$$\begin{aligned} a_k(n) &= c_{k0} + c_{k1} (n - n_a^i)^1 + \dots + c_{kp} (n - n_a^i)^{p(n)} \\ \varphi_k(n) &= \epsilon_k + 2\pi k\zeta (n - n_a^i) \end{aligned}$$

where $p(n)$ is the order of the amplitude polynomial, which is, in general, a time-varying parameter.

RESIDUAL (NOISE) PART

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The non-periodic part is just the *residual* signal obtained by subtracting the periodic-part (harmonic part) from the original speech signal in the time-domain

$$r[n] = s[n] - h[n]$$

where $h[n]$ is either $h_1[n]$, $h_2[n]$, or $h_3[n]$.

PARAMETERS ESTIMATION

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- Pitch: based on an autocorrelation criterion
 - Maximum Voiced Frequency: voicing matching criteria
 - Amplitudes: Least-Squares
 - Noise part: variance and Linear prediction

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EXAMPLE OF ESTIMATION

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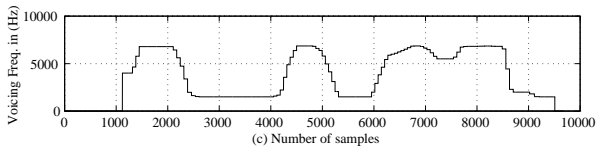
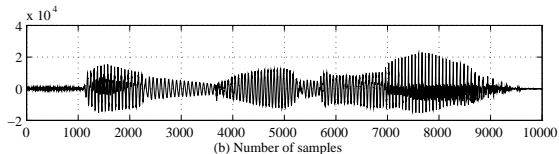
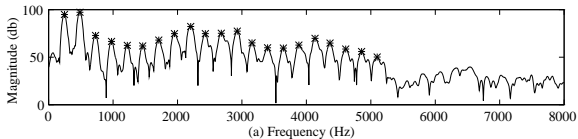
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FUNDAMENTAL FREQUENCY REFINEMENT

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Using the initial f_0 value and the L detected voiced frequencies f_i , then the refined fundamental frequency, \hat{f}_0 is defined as the value that minimizes the error:

$$E(\hat{f}_0) = \sum_{i=1}^L |f_i - i \cdot \hat{f}_0|^2$$

REFINEMENT FREQUENCY EXAMPLE

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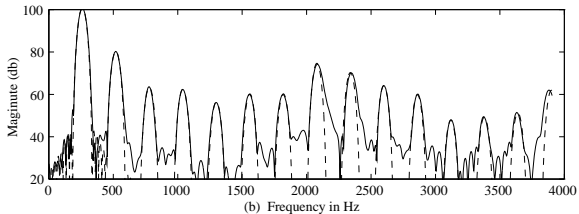
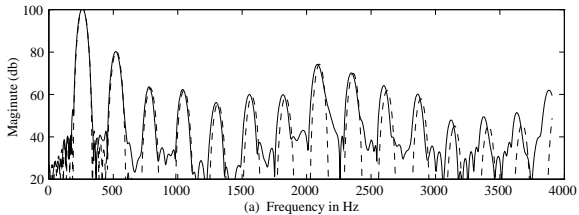
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VARIANCE OF THE RESIDUAL SIGNAL

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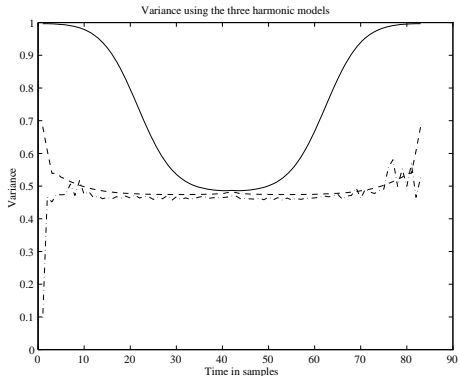
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References

- Direct time frequency matching
 - For the periodic part: Overlap-and-Add, or
 - Linear amplitude interpolation
 - Linear phase interpolation using average pitch value
 - For the stochastic (noise) part):
 - Instead of AR coefficients we use reflection coefficients
 - Sample-by-sample filtering of Gaussian noise using normalized lattice filtering
 - Modulation in time with a deterministic function (i.e., triangular)

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PREPARING FOR PROSODY MODIFICATIONS

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References

For being able to make prosodic modifications (at least pitch and time scale modifications) in the context of HNM, we should

- Associate analysis and synthesis time instants
- Determine a continuous magnitude envelope
- Determine a continuous phase envelope

PREPARING FOR PROSODY MODIFICATIONS

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PREPARING FOR PROSODY MODIFICATIONS

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MAGNITUDE: DISCRETE CEPSTRUM

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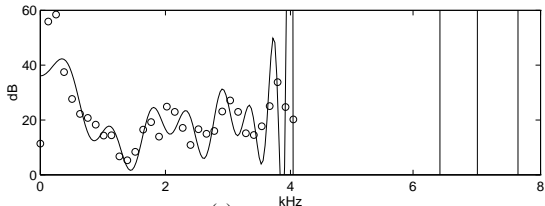
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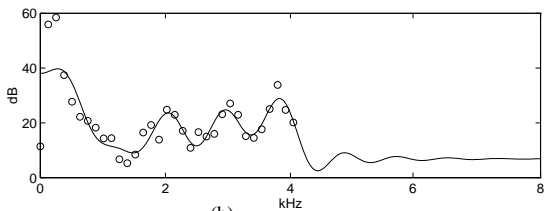
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(a)



(b)

BARK SCALED DISC. CEPSTRA

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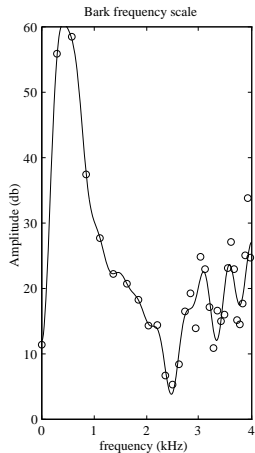
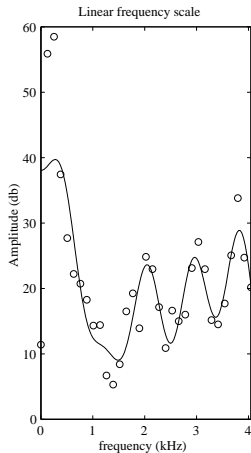
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PHASE ENVELOPE ESTIMATION

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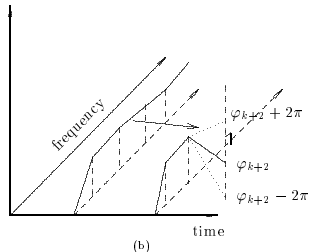
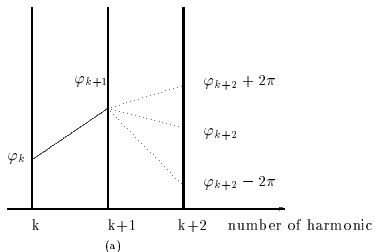
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EXAMPLE OF PHASE ENVELOPES

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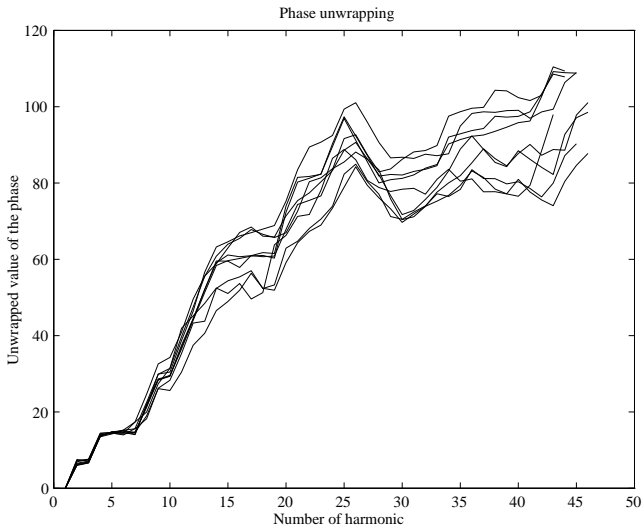
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EXAMPLE OF PITCH MODIFICATION

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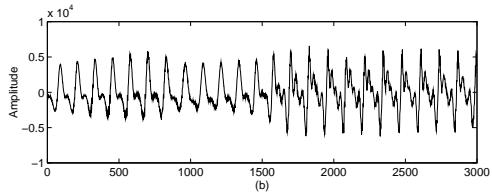
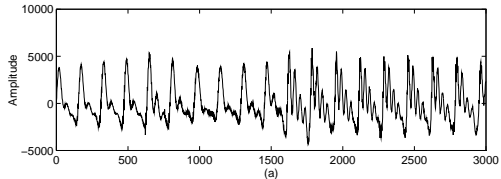
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Pitch modification by 1.3

SOUND EXAMPLES

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Original



Time-scale by 0.7



Time-scale by 1.6



Pitch modification by 0.8



Pitch modification by 1.6



Original



Time-varying pitch and time modif.



Original



Time-scale by 4



Time-scale by 6



PROBABILISTIC CLASSIFICATION

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References

- Modeling of the acoustic space of a speaker by a GMM :

$$p(\mathbf{x}) = \sum_{i=1}^m \alpha_i N(\mathbf{x}; \boldsymbol{\mu}_i, \boldsymbol{\Sigma}_i),$$

- Classification:

$$P(C_i|\mathbf{x}) = \frac{\alpha_i N(\mathbf{x}; \boldsymbol{\mu}_i, \boldsymbol{\Sigma}_i)}{\sum_{j=1}^m \alpha_j N(\mathbf{x}; \boldsymbol{\mu}_j, \boldsymbol{\Sigma}_j)}$$

- Estimation using an Expectation-Maximization (EM) algorithm initialized by a standard binary splitting VQ procedure.

MAPPING FUNCTION

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- Mapping function [7]:

$$\mathcal{F}(\mathbf{x}_t) = \sum_{i=1}^m P(C_i|\mathbf{x}_t) [\boldsymbol{\nu}_i + \boldsymbol{\Gamma}_i \boldsymbol{\Sigma}_i^{-1}(\mathbf{x}_t - \boldsymbol{\mu}_i)]$$

- Motivation:

$$E[\mathbf{y}|\mathbf{x} = \mathbf{x}_t] = \boldsymbol{\nu} + \boldsymbol{\Gamma} \boldsymbol{\Sigma}^{-1}(\mathbf{x}_t - \boldsymbol{\mu})$$

- Estimation of mapping function:

$$\epsilon = \sum_{t=1}^n \|\mathbf{y}_t - \mathcal{F}(\mathbf{x}_t)\|^2$$

MAPPING FUNCTION

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Yannis
Stylianou

Outline of the
talk

HNM

Modifications
with HNM

Source

Filter

References

- Mapping function [7]:

$$\mathcal{F}(\mathbf{x}_t) = \sum_{i=1}^m P(C_i|\mathbf{x}_t) [\boldsymbol{\nu}_i + \boldsymbol{\Gamma}_i \boldsymbol{\Sigma}_i^{-1}(\mathbf{x}_t - \boldsymbol{\mu}_i)]$$

- Motivation:

$$E[\mathbf{y}|\mathbf{x} = \mathbf{x}_t] = \boldsymbol{\nu} + \boldsymbol{\Gamma} \boldsymbol{\Sigma}^{-1}(\mathbf{x}_t - \boldsymbol{\mu})$$

- Estimation of mapping function:

$$\epsilon = \sum_{t=1}^n \|\mathbf{y}_t - \mathcal{F}(\mathbf{x}_t)\|^2$$

MAPPING FUNCTION

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PERFORMANCE OF THE MAPPING FUNCTION

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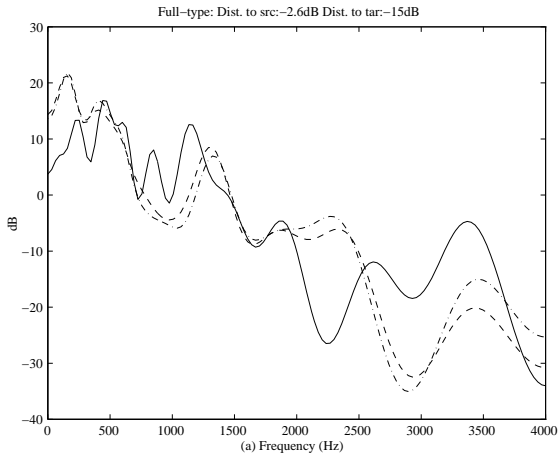
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RESULTS - XAB TEST

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Task: Listeners were asked to select either A or B as being most similar to X.

	PO	16 GMM	64 GMM	64 GMM(2)
Correct answers	18%	83%	88%	97%

AUDIO EXAMPLES OF VOICE CONVERSION: HNM + GMM

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Source		Converted		Target	
Source		Converted		Target	

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